





# AVIATION TWIN TRANSITION CLUSTER

A EUROPEAN INITIATIVE FOR A SUSTAINABLE FUTURE







# RefMap Clustering Event 2025

Advancing Sustainable Aviation & Urban Air Mobility

### AIRSHIP: Autonomous Electric Ground-Effect Cargo Craft

Zorana Milosevic, Universidad Politécnica de Madrid









#### A bit about me

- PhD in Automation & Robotics
- Studies & research:
  - Universidad Politécnica de Madrid, Spain
  - Tampere University, Finland
  - University of Belgrade, Serbia
- Developing autonomous robotic systems
  - Underwater, mining, flying
- AIRSHIP Project Coordinator



ZORANA MILOSEVIC Universidad Politécnica de Madrid, Spain zorana.milosevic@upm.es









### Autonomous Flying Ships for Inter-Island and Inland Water **Transport**

- HORIZON-RIA project
- 5 M€
- TRL 4-5
- 48 months, 01.01.2023-31.12.2026
- 7 partners





















# Main Objectives



#### Lay the foundation for a new class of vehicle

- UWV Unmanned WIG Vehicle
- Fully electrical unmanned system

#### Solve technological challenges

- Stable low altitude flight
- Advanced control algorithms: adaptive, RL
- Obstacle avoidance
- Limited weight and space
- Zero-emissions power system: integration of solar energy and fuel cells

#### New business models

- Compare AIRSHIP technology to traditional shipping, road, rail
- Estimate the potential profit of the transport
- Possible cargo routes
- Legal aspects

#### **Sustainability**

- Environmental footprint
- Ethics
- Social impact

#### **Raise awareness**

• Educate on flying ships











#### **Short history**

- Ground effect vehicle / ekranoplan
- Toivo Kaario first prototype 1935
- Biggest ever Caspian Sea monster 1966







#### Ground effect in Nature









**SOURCE** 



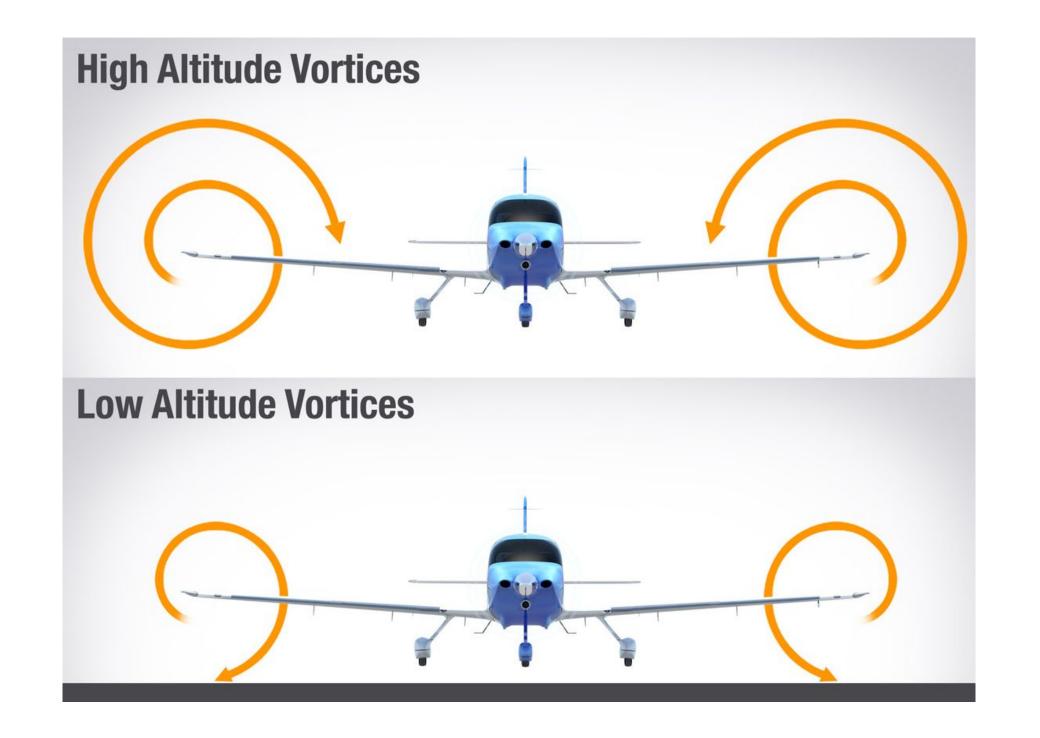






#### **Ground Effect**

- Decreased drag
- Less power
- More payload















#### Flying ship - UWV

- Unmanned Wing-In-Ground Vehicle
- Operating close to surface
- Faster than a ship
- More payload than an airplane







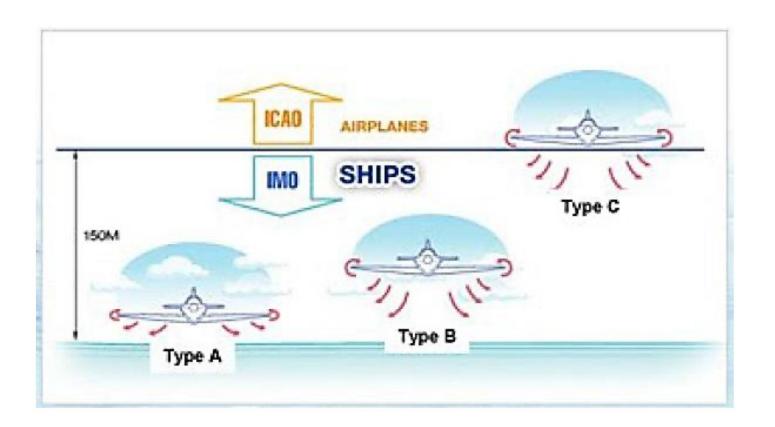






#### A plane or a ship?

- IMO classifies it as a ship
- Interacting with the surface











### Take off & Landing

From water to water











#### Access to areas without infrastructure

- Floods
- Volcano eruption
- Humanitarian catastrophe
- Any area with water access













#### **Autonomous Operations**

- Sensors for situational awareness
  - Radar, lidar, stereo-cameras, GNSS, INS
- Obstacle avoidance
- Optional remote control





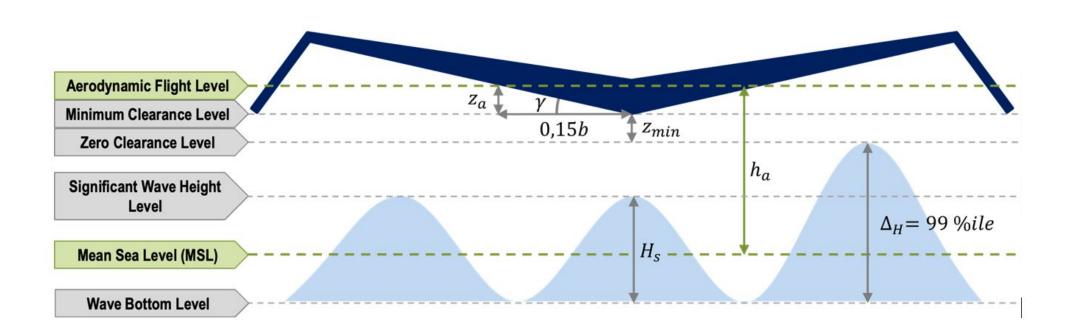






#### Seaworthiness

- Optimal flying height is half of the wingspan
- Can fly higher in case of heavy seas
- Control system will handle rogue waves





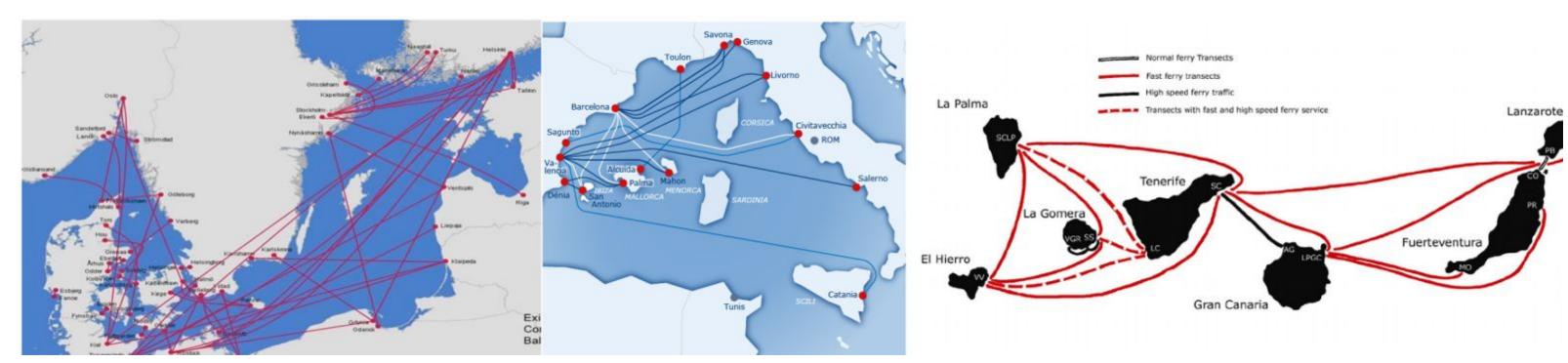






#### **Ideal locations**

- Mid-range distances
  - Mediterranean sea
  - Canary islands
  - Greek islands













#### **Future**

- Design scalable between 5m and 25m
- Payload between 50kg and 7 tons







### AIRSHIP prototypes





Parameter	CC / Commercial Concept	A-1 / Technology Demonstrator
Scale	1:1	1:5
Wingspan	25 m	5 m
MTOW	16 000 kg	120 kg
Payload	7 000 kg	20 kg
Cruise speed	120 kn (220 km/h)	55 kn (100 km/h)
Cruise power	350 <i>kW</i>	1,5 kW
Take-off speed	65 kn (120 km/h)	40  kn (70km/h)
Take-off power	1000 kW	4,5 <i>kW</i>
Range	1000 km	
Lift-to-drag ratio	18,5	_





#### **®** ≪ refmap



# thank you for your attention!

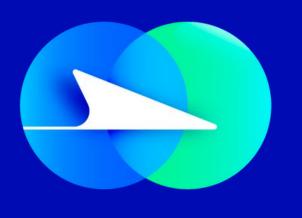


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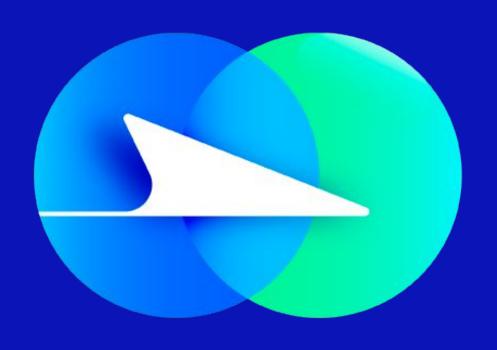
For more information: www.refmap.eu

# Q&A/Closing









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