





AVIATION TWIN TRANSITION CLUSTER

A EUROPEAN INITIATIVE FOR A SUSTAINABLE FUTURE







RefMap Clustering Event 2025

Advancing Sustainable Aviation & Urban Air Mobility

Progress and Challenges in Noise Modelling and Assessment of Innovative Air Mobility

Prof. Antonio J Torija, University of Salford







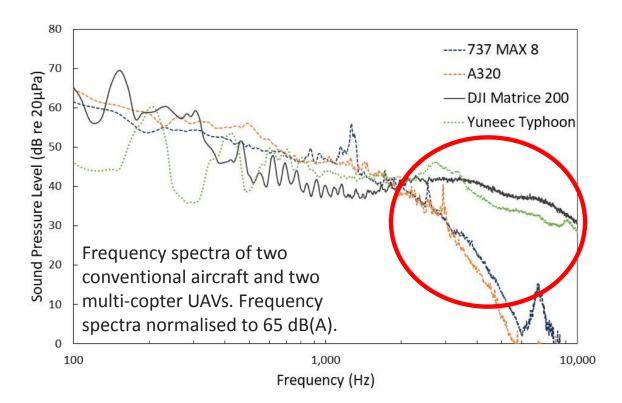


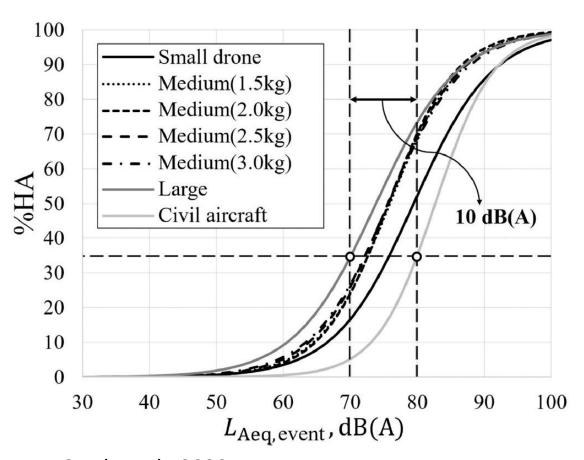




IAM Noise Signature

- IAM noise perceived as more annoying than conventional aircraft/rotorcraft (same sound levels)
- The noise signature if IAM is rather complex, and doesn't resemble conventional aircraft or rotorcraft
 - Highly tonal (and complex tonality)
 - Significant content in high frequencies
 - Unsteady noise emission (changes over time)





Gwak et al., 2020



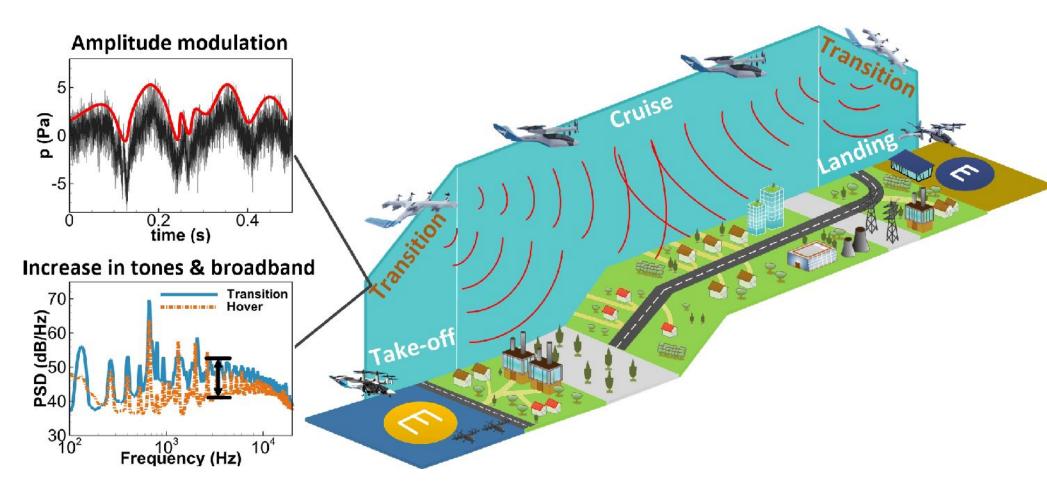






IAM Operating Conditions

- Unconventional operating conditions (e.g., hover-to-forward flight transition)
- Operating in urbanised environments, and closer to people
- Challenge of unsteady and loud operating conditions near ground.





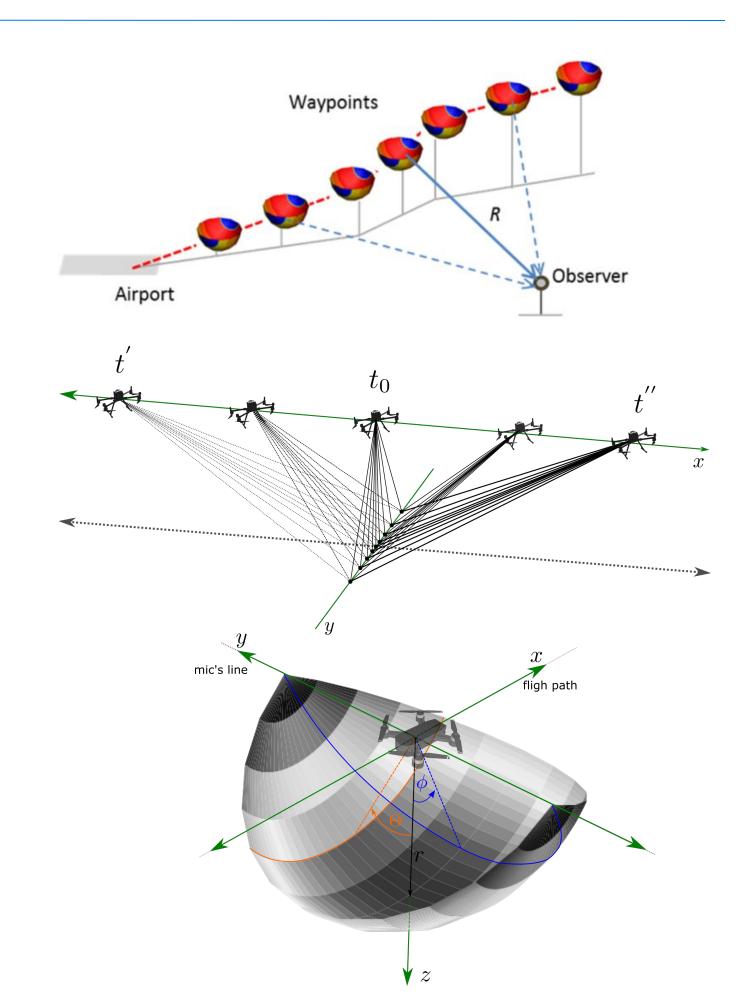






IAM Noise Hemispheres

- Noise hemispheres needed to capture amplitude, frequency and directionality information.
- Aligned to EASA NORAH2 model
- Challenge:
 - Complex noise field measurements
 - Noise prediction (models yet to be developed or highly complex)



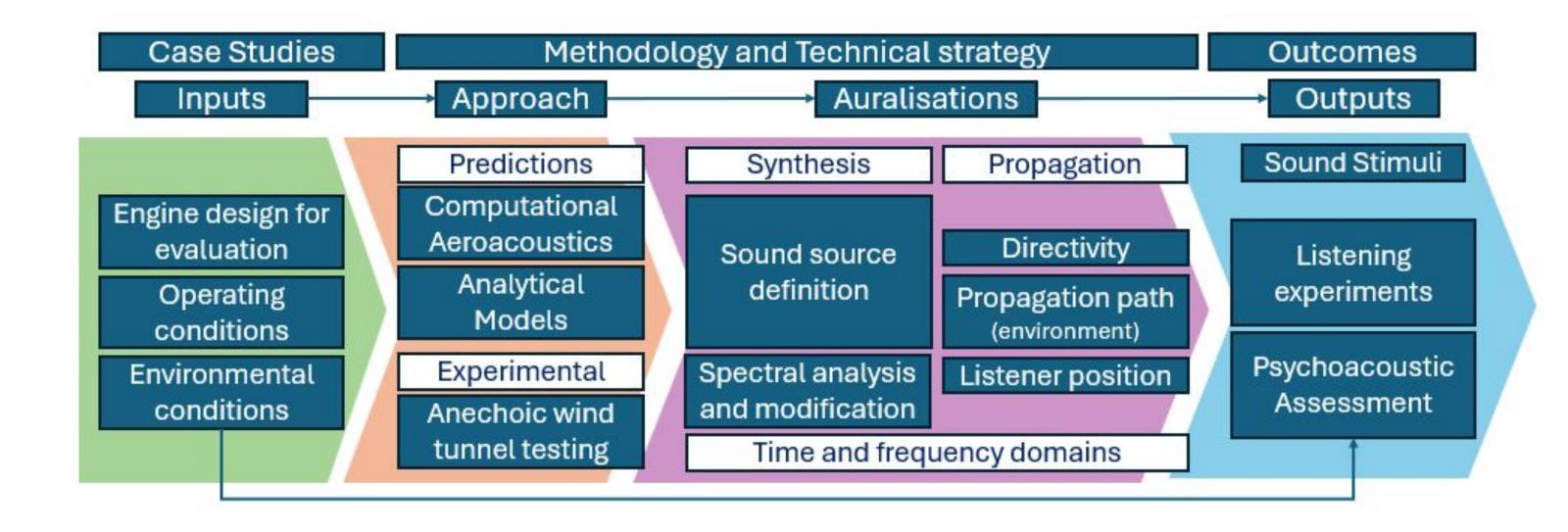








Salford's IAM Noise Framework





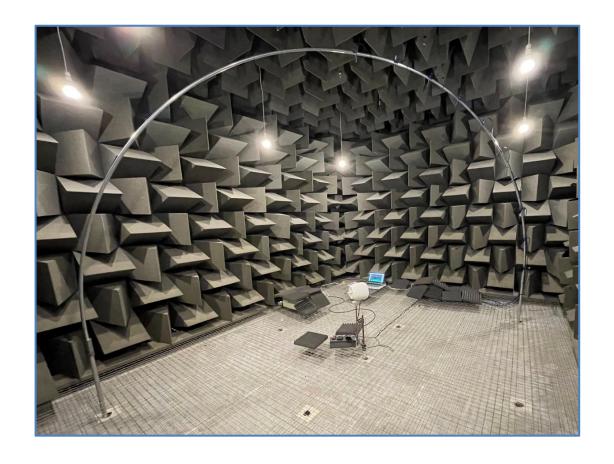






Salford's Acoustic Laboratories

- Leading research on IAM noise
 - Aeroacoustics / Noise Modelling
 - Psychoacoustics







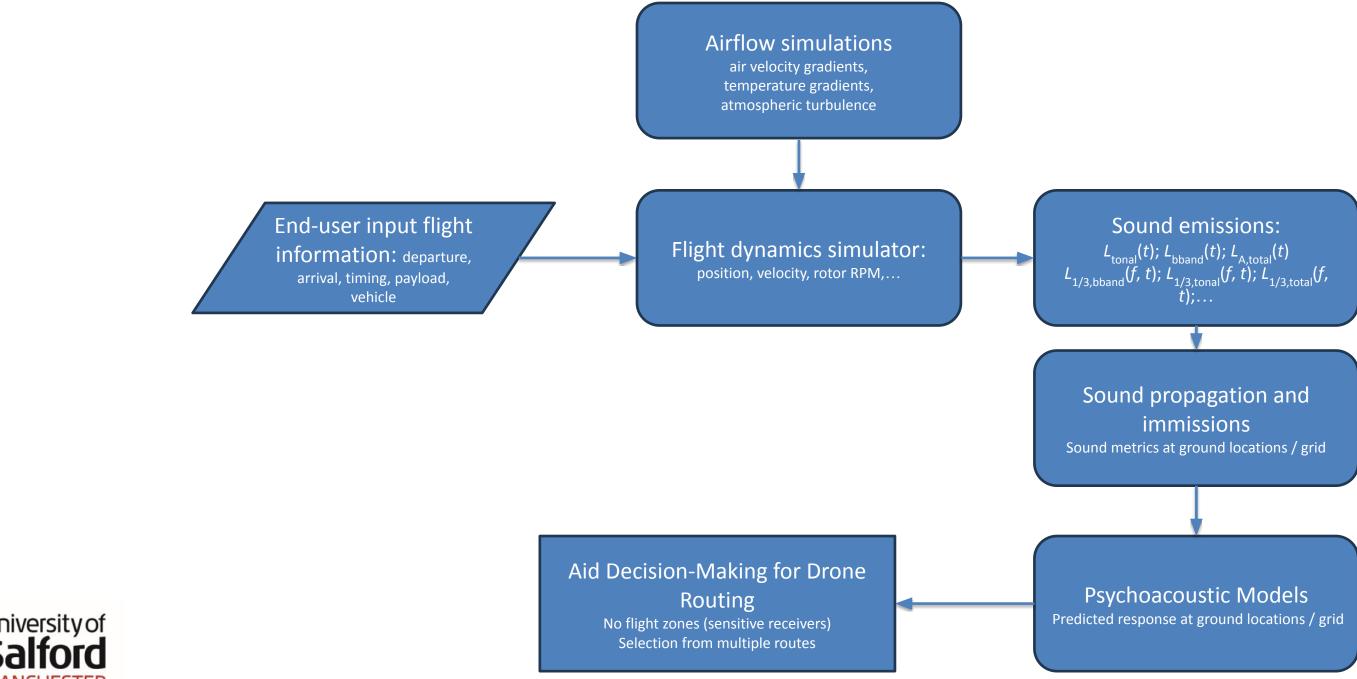








Salford's Contributions - RefMap



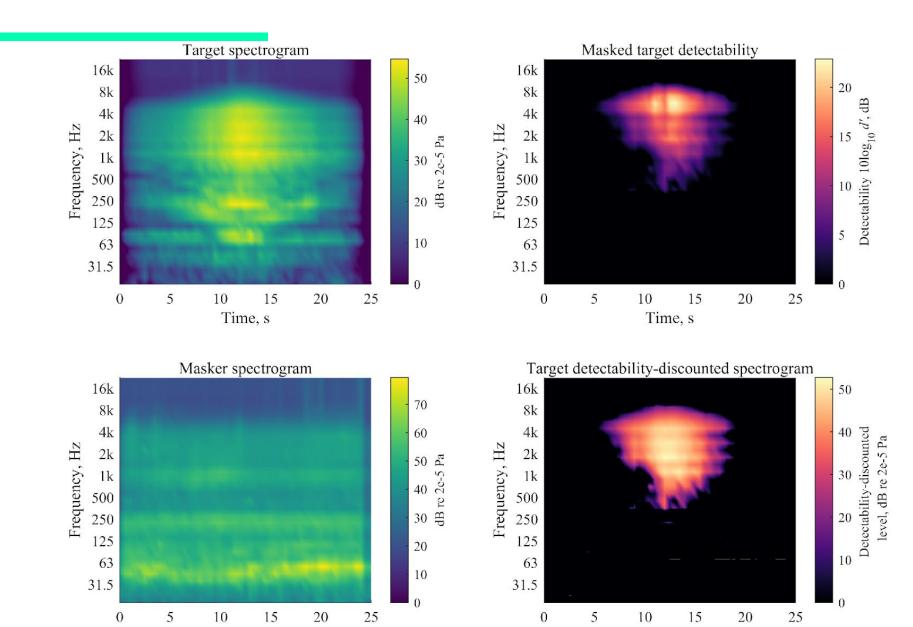




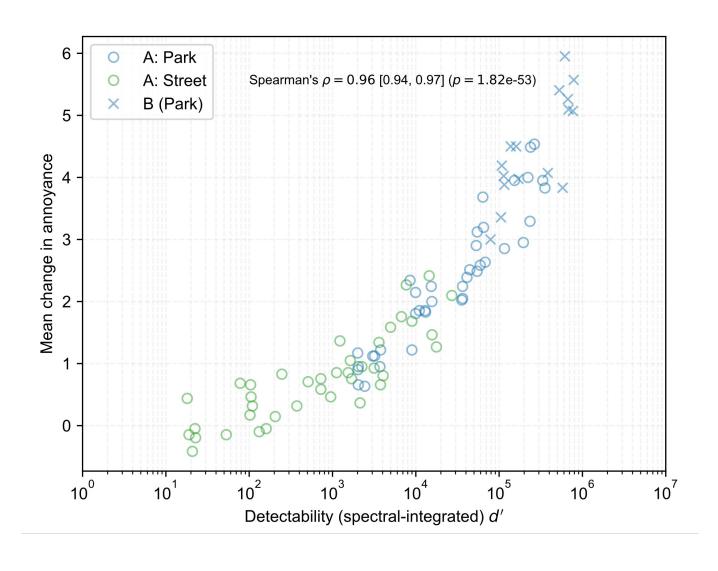




Salford's Contributions - RefMap



Time, s





Time, s



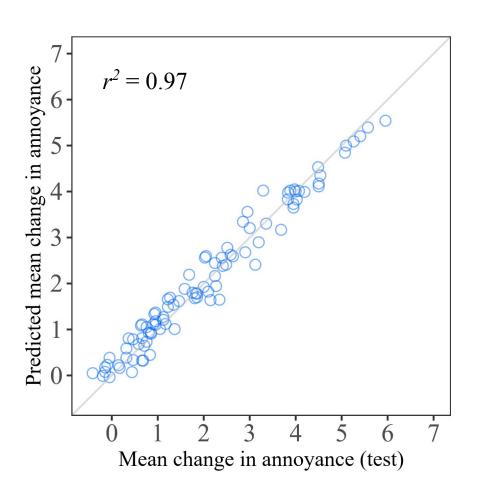


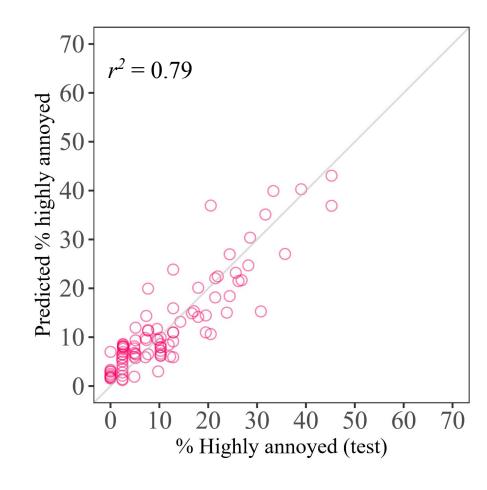


Salford's Contributions - RefMap

Statistical models* for change in annoyance (with UAS vs without), and %highly annoyed based on key variables:

- •relative sound level ΔL_{AF} or detectability d'
- •Sharpness S (high frequency balance)
- •Tonal loudness T_N (hum / whine / buzz)
- •(interaction $S \times T_N$)
- Flight events quantity







^{*}Generalised estimating equations solution for generalised linear models







Salford's Contributions - ImAFUSA

Athens - Egaleo Park

- 110 participants (5x groups)
- 3x altitudes (10 m / 20 m / 30 m)
- DJI Mavic 3 drone (1 kg)
- 2x soundscape 'zones'
- CityTraffic
- GreenSpace
- Take-off / flyby / landing
- Soundwalk route reversed for two groups



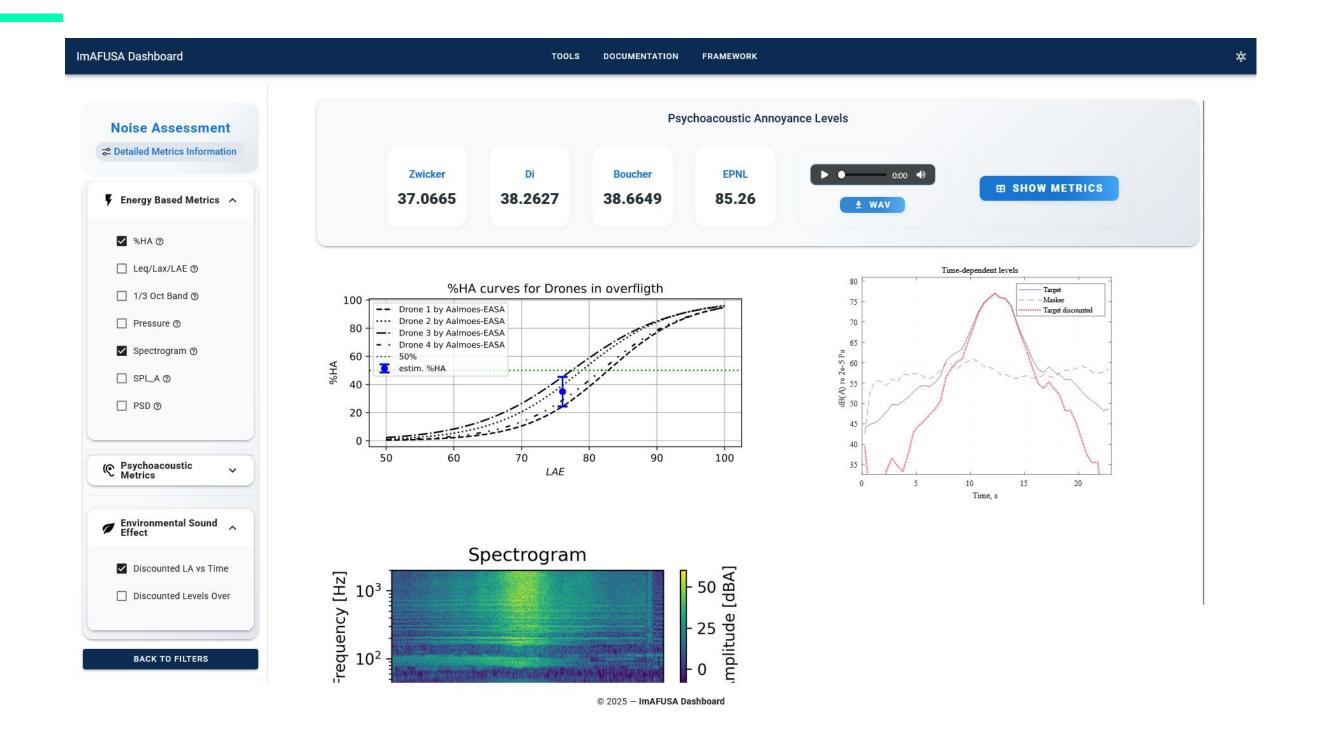








Salford's Contributions - ImAFUSA







thank you for your attention!

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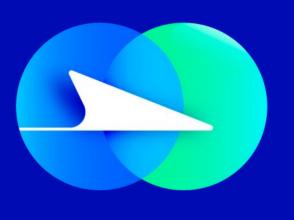








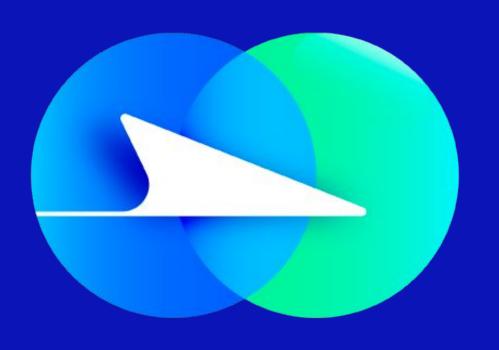
Q&A/Closing



For more information: www.refmap.eu







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